

Solar O&M System for Solar Power Plant Efficiency Maintenance

Sun Robot®

ECOSENSE Solar Panel Cleaning Robot

Scan-type Solar Panel Cleaning Robot [ES-SRS]

suitable for large & long solar power plant

Vertical-type Solar Panel Cleaning Robot [ES-VSM]

uitable for rooftop or wide solar power plant

Solar Panel Surface Inspection Equipment [ES-ISR]

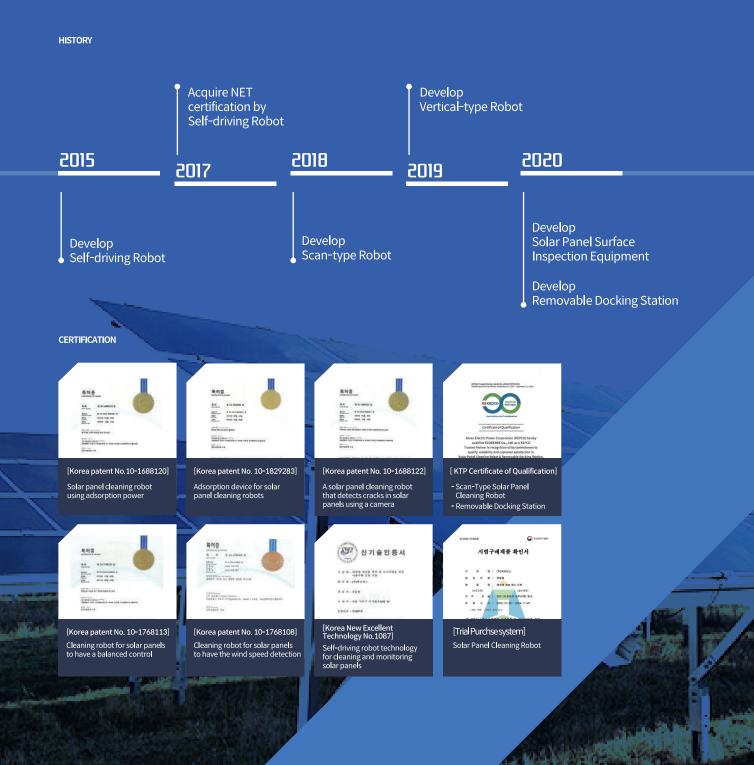
for inspect solar panels short circuits

Removable Docking Station [ES-MRS]

for move cleaning robot between solar power plant arrays

Solar Power Plant

It's time to focus on Maintenance



ECOSENSE' SunRobot can...

Applicable to various environments of solar power plant

Cleaning Robot – Stationary [Scan–Type ES–SRS] & Mobile [Vertical–Type ES–VSM] For Move Cleaning Robot between Arrays – Removable Robot Station [ES–MRS] For Inspect Solar Panels short circuits – Inspection Equipment [ES–ISR]

We offer customized products.



Problems Characteristics and Current Problems of Solar Power Plant - Lack of awareness of improvement in power generation efficiency (5-10%) due to cleaning - Insufficient maintenance/management activities due to installation-oriented policies - Safety issues occur when cleaning manually - Shortening solar panel life in absence of cleaning - Many panels exist that cannot be cleaned manually - Inspection takes a long time in case of damage to the solar power plant panel Effect Effectiveness through continuous Maintenance/Management - Extended Life of Solar Power Plants - Improvement of solar power plant efficiency degradation due to pollution (5-10% improvement) - Automatic panel damage check - Extend panel life and improve efficiency through real-time panel cleaning - Eliminate safety issues caused by manual cleaning





Scan-type Solar Panel Cleaning Robot





- It can be installed regardless of the slope or width of the solar panel
- If there is a gap between arrays, connect it with a rail and install it
- Suitable for large solar power plants installed with high-slope and long arrays

Vertical-type Solar Panel Cleaning Robot

ES-VSM



- Suitable for wide areas
- Can be carried by humans to clean small solar plant
- Suitable for rooftop Solar Plant



Removable Robot Station

Removable Docking Station

ES-MRS

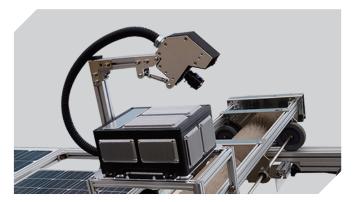


- A Removable Docking Station that allows the Solar Panel Cleaning Robot to move between arrays
- It is possible to reduce investment costs by improving the efficiency of using expensive robot
- Can improve performance compared to investment
- Suitable for small solar power plants with short lengths

Panel Inspection Equipment

Solar Panel Surface Inspection Equipment

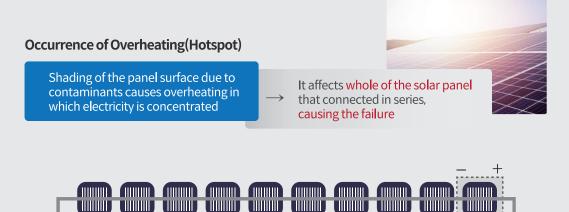
ES-ISR



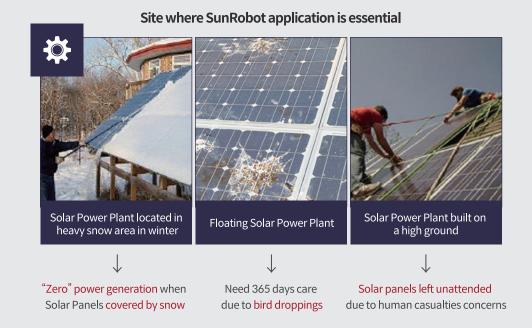
- Solar Panel circuit short inspection equipment
- Manual inspection difficult for large solar power plant
- Preventing reduction in power generation efficiency due to damage to panels
- Improves loss due to drone or manual inspection

Maintenance of Solar Power Plant,

Problems that arise when solar panels are left unattended



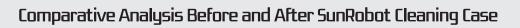
Affects 9 cells connected in series

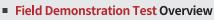




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SunRobot can take responsibility





- Test Site : D Power Plant in Korea
- Test Period : January 2019, for a month
- Test Result :
- power generation efficiency **7.7**% **†** improved
- Snow removal capacity 90% ↑ or more
- KTL(Korea Testing Laboratory) Test Result
 - power generation efficiency 13.2% 1 improved





Before cleaning



After cleaning



Installation site in power plant

Comparison of status before and after cleaning (snow)



Before cleaning



After cleaning



Scan-type Solar Panel Cleaning Robot (ES-SRS)

Scan-type Solar Panel Cleaning Robot suitable for large & long solar power plant

Key application techniques

Module Assembly Design

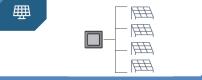
- robot cleaner part can be connected and disconnected depending on the panel arrangement
- Simplify and lighten robot structure for easy connection and disconnection
- Easy installation and affordable entry-level robot for commercial and home use





- Module type of structure allows extension depends on panel size (standard 1.5~9m)
- Automatic control cleaning speed by environment

🌣 Features



Snow/Rain Auto Detection

- Moving speed control standard 40m/min(2.4km/h) Maxmum(snow) 60m/min(3.6km/h)



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- Movable self-charging 2001 (Optional)
 Battery 2 hours charging and 4 hours using



Module Assembly type

- Module assembly (standard 1.5~9m)
 Various width of panels available
 Customized manufacturing
 Reducing price as module type mass production (20% cheaper than other)



Timer setting

- Remote control is available using laptop, application and etc.



Wheels attached in each modules to prevent bending
Prevent slippery using stable moving in snow and rain
High speed moving

(2 to 4 times high speed compare other)

Spiral type Brush

Stable Moving Body

- Maximization dust removal effect
 Product design for easy brush replacement

Specifications

Category	Capacity	Category	Capacity
Name	Scan-type Solar Panel Cleaning Robot	Battery Type	LiFePO4
Model	ES-SRS	Charging time	2h
Power Consumption	170W	Driving Time	4h
Rated Voltage	24V	Cleaning Mode	Manual / Auto(Timer setting)
Driving Speed(*)	25 ~ 60m/min	Cleaning Efficiency	80~240m³/min
Climbing Capacity	 30 ± 5°	Total Weight	54kg (standard 1.5m X 2ea)
Operating Temperature	-20 ~ 70°C	Size	W540 X L3200 X H320 (mm)

Vertical-type Solar Panel Cleaning Robot [ES-VSM]

Vertical-type Solar Panel Cleaning Robot suitable for rooftop or wide solar power plant

Key application techniques

Solar Panel Cleaning Robot Drive Platform Technology

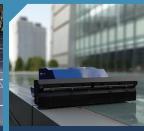
- Driving by guide
- Vertical Driving and Docking
- Slopeable Drive System
- Adsorption Drive Mechanism
- Lift Rotation Mechanism to prevent damage to Solar Pane

Location recognition and automatic control technology

- Autonomous Driving Algorithm
- Gap detection and outline detection technology







2018, R Rooftop Glass Ceiling

- Clean more than 140m^{*}/h

- Vertical(lift) driving minimizes panel damage
- Charged using the top auxiliary solar panel

🌣 Features



Cleaning Stains with Brushes

- Moving on the solar panel to zigzag driving mode, spray cleaning liquid, and clean it with a brush



Stable Docking System

 Adopt a guide to move the top of the solar panel
 Horizontal movement is possible through the robot's guide device without additional rail installation



Vertical Self-Driving

- A robot that is separated from the main body and can drive vertically cleans wide solar panels



Charging with Auxiliary Charging Unit (10W solar panel

- Auxiliaryly charge the robot via a solar panel installed on the robot top

Specifications

Category	Capacity	Category	Capacity
Name	Vertical-type Solar Panel Cleaning Robot	Battery Type	LiFePO4
Model	ES-VSM	Charging time	3h
Power Consumption	70W	Driving Time	5h
Rated Voltage	24V	Cleaning Mode	Manual / Auto(Timer setting)
Driving Speed(*)	8~11 m/min	Cleaning Efficiency	140m²/min
Climbing Capacity	5~40°	Total Weight	25kg
Operating Temperature	-20∼70°C	Size	W730 X L630 X H260 (mm)

(*) Depends on installation site

Removable Docking Station [ES-MSR]

Removable Docking Station for move cleaning robot between solar power plant arrays

Characteristics

- A Removable Docking Station that allows the Solar Panel Cleaning Robot to move between arrays
- Suitable for small Solar power plants with multiple, narrow panel arrays
- Can improve performance compared to investment





Docking station movement

🌣 Features



Solar Power Self-charging

- Stationary self-charging 400W - Battery 2 hours 30 minutes charging and 5 hours using



Move Location

- Move along installed rails
 4-wheel motor provides high travel stability
 Position recognition using mechanical sensors
 Array position recognition via limit switch



Angle Setting

- Adjust the station height to facilitate the movement of the cleaning robot
 Can adjust the height of the station's top and bottom at the same time



Return to Original Position

- Auto-return after all array cleaning is complete
 Perform self-origin adjustment after return to original position
 Self-origin adjustment prevents motion errors

Specifications

Category	Capacity	Category	Capacity
Name	Removable Docking Station	Battery Type	LiFePO4
Model	ES-MRS	Charging time	2h 30min
Power Consumption	200W	Driving Time	5h
Rated Voltage	24V	Cleaning Mode	Manual / Auto(Timer setting)
Driving Speed(*)	10m/min	Operating Temperature	-20~70°C
Angle Setting Time	1min 30cec	Size	W540 X L3200 X H320

(*) Depends on installation site

Solar Panel Surface Inspection Equipment [ES-ISR]

Solar Panel Surface Inspection Equipment that can automatically inspect all solar panels for faults

Characteristics

- Automatically inspect solar panel surfaces while moving
- Real-time transmission of accurate location of fault panels, such as short circuits on panels





Inspect Solar Panels

🌣 Features



Characteristics

- Contactless inspection sensor
 Utilize multiple/multiple sensors
- Thermal imaging camera mountable Detachable inspection equipment



Inspection

- Broken Circuit Inspection
 Inspection of breakage
 IV TEST
 Module fault check
- IV TEST
- Inspect Panel Surface Cracks





- Defect detection rate: 90%
 Diagnostic accuracy 97%
 IP55



Defect Detection

- Save events and notify users when faults are
- detected Check the Fault Panel Image on the Monitoring Server

Specifications

Category	Capacity	Category	Capacity
Name	Solar Panel Surface Inspection Equipment	Operating Temperature	- 20 ~ 70°C
Model	ES-IRS	Size	W260 x L400 x H375 (mm)
Panel Defect Detection Accuracy	92%	Panel Diagnostic Fault Accuracy	95%
IP	55		



Solar 0&M System for Solar Plant Efficiency Maintenance



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